

## 7.1 EIGENSYSTEMS

[BRIEF VERSION]

①

### ① MOTIVATION FROM ODE'S

#### (i) SCALAR ODE'S

RECALL: IF  $x: [0, \infty) \rightarrow \mathbb{R}$  SATISFIES IVP

$$\begin{cases} \frac{dx}{dt} = ax \\ x(0) = x_0 \end{cases}$$

①

Then  $x(t) = x_0 e^{at}$

#### (ii) VECTOR-VALUED ODE'S

SUPPOSE IF  $\vec{x}: [0, \infty) \rightarrow \mathbb{R}^n$  SATISFIES IVP

$$\begin{cases} \frac{d\vec{x}}{dt} = A\vec{x} & \text{where } A \text{ is } n \times n \\ \vec{x}(0) = \vec{x}_0 \end{cases}$$

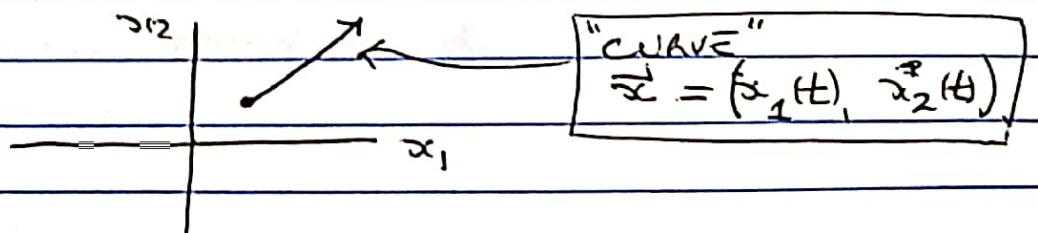
②

EX

$$\frac{d\vec{x}}{dt} = \begin{pmatrix} 0 & 1 \\ 6 & -1 \end{pmatrix} \vec{x} \iff \begin{cases} \frac{dx_1}{dt} = x_2 \\ \frac{dx_2}{dt} = 6x_1 - x_2 \end{cases}$$

③

OFTEN  $\exists$  STRAIGHT LINE SOLUTIONS:



## MOTIVATION + INTERPRETATION

(1B)

Consider  $x = x(t)$  satisfying

$$\frac{d^2x}{dt^2} + \frac{dx}{dt} - 6x = 0 \quad (1)$$

with initial conditions

$$x(0) = x_0$$

$$\frac{dx}{dt}(0) = v_0$$

SET  $y = \frac{dx}{dt}$

Then (1) says

$$\frac{dy}{dt} + y - 6x = 0$$

$$\frac{dx}{dt} - y = 0$$

OR  $\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 6 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \quad (2)$

$$\begin{pmatrix} x \\ y \end{pmatrix}(0) = \begin{pmatrix} x_0 \\ v_0 \end{pmatrix}$$

$$\boxed{\frac{d\vec{x}}{dt} = A\vec{x}}$$

CLAIM  $\vec{x}(t) = c_1 e^{2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 e^{-3t} \begin{pmatrix} -1 \\ 3 \end{pmatrix}, \quad c_1, c_2 \in \mathbb{R}$   
is (general) solution to (2) (3)

CHECK

(1c)

$$\frac{d\vec{x}}{dt} = c_1 e^{2t} 2 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 e^{-3t} 3 \begin{pmatrix} -1 \\ 3 \end{pmatrix}$$

$$A\vec{x} = c_1 e^{2t} A \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 e^{-3t} A \begin{pmatrix} -1 \\ 3 \end{pmatrix}$$

and

$$A \begin{pmatrix} 1 \\ 2 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \quad A \begin{pmatrix} -1 \\ 3 \end{pmatrix} = 3 \begin{pmatrix} -1 \\ 3 \end{pmatrix}$$

is easy to check

□

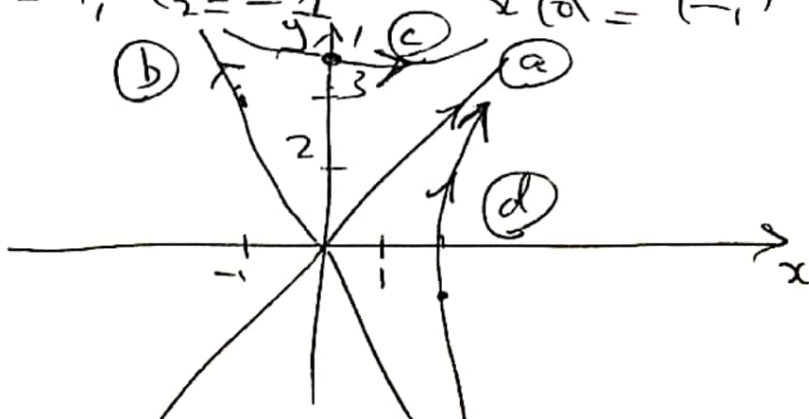
NOTICE By (3)

(a)  $\lim_{t \rightarrow +\infty} \vec{x}(t) = c_1 e^{2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix} \leftarrow \text{STRAIGHT LINE SOLUTIONS}$

(b)  $\lim_{t \rightarrow -\infty} \vec{x}(t) = c_2 e^{-3t} \begin{pmatrix} -1 \\ 3 \end{pmatrix}$

(c) IF  $c_1 = c_2 = 1$  then  $\vec{x}(0) = \begin{pmatrix} 0 \\ 5 \end{pmatrix}$

(d) IF  $c_1 = 1, c_2 = -1$  then  $\vec{x}(0) = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$



(2)

GUESS FORMULA

$$\vec{x}(t) = f(t) \vec{v} \quad (4) \quad \begin{array}{l} f: [0, \infty) \rightarrow \mathbb{R} \\ \vec{v} \in \mathbb{R}^n \text{ FIXED} \end{array}$$

PLUG INTO (3)

$$f'(t) \vec{v} = A f(t) \vec{v}$$

$$\Rightarrow \underbrace{\frac{f'(t)}{f(t)}}_{\text{SCALAR}} \vec{v} = \underbrace{A}_{t\text{-INDEPENDENT}} \vec{v}$$

FORCES

$$\frac{f'(t)}{f(t)} = \lambda = t\text{-INDEPT CONSTANT}$$

SO GET

$$f'(t) = \lambda f(t) \quad (5)$$

$$\text{AND } A \vec{v} = \lambda \vec{v} \quad (6)$$

LIKE  
SEPARATION OF  
VARIABLES  
IN PDES

$$\text{SOLUTION OF (5) IS } f(t) = f_0 e^{\lambda t}$$

(6) IS AN EIGENVALUE-EIGENVECTOR PROBLEM  
FOR  $n \times n$  MATRIX  $A$



(3)

## (B) THE EIGENPROBLEM

DEF 1 GIVEN  $n \times n$   $A$  IF  $\lambda \in \mathbb{C}$  AND  $0 \neq \vec{v} \in \mathbb{C}^n$  SATISFY

$$A \vec{v} = \lambda \vec{v}$$

- WE CALL -  $\lambda$  AN EIGENVALUE OF  $A$   
 -  $\vec{v}$  AN EIGENVECTOR OF  $A$   
 -  $(\lambda, \vec{v})$  IS AN EIGENPAIR  
 -  $\sigma(A) =$  SET OF ALL EIGENVALUES OF  $A$   
 = SPECTRUM OF  $A$ .

OBSERVE

$$\begin{aligned} A \vec{v} = \lambda \vec{v} &\Leftrightarrow (A - \lambda I) \vec{v} = \vec{0} \\ &\Leftrightarrow \vec{v} \in N(A - \lambda I) \end{aligned}$$

$\therefore$

THM 2

- ①  $\lambda \in \sigma(A) \Leftrightarrow N(A - \lambda I) \neq \{\vec{0}\}$   
 $\Leftrightarrow A - \lambda I$  IS NOT INVERTIBLE  
 $\Leftrightarrow p(\lambda) := \det(A - \lambda I) = 0$   
 - CHARACTERISTIC EQN FOR  $A$

- ② THE SET OF EIGENVECTORS OF  $A$  WITH EVALUE  $\lambda$   
 = NON-ZERO ELTS OF  $N(A - \lambda I)$

$\lambda$ -EIGENSPACE OF  $A$

(C) SCAFFOLDED PROBLEM TO SOLVE ODE SYSTEM

(4)

$$\begin{cases} \frac{d\vec{x}}{dt} = \begin{pmatrix} 0 & 1 \\ 6 & -1 \end{pmatrix} \vec{x} \\ \vec{x}(0) = \begin{pmatrix} 2 \\ 5 \end{pmatrix} \end{cases} \quad A = \begin{pmatrix} 0 & 1 \\ 6 & -1 \end{pmatrix}$$

- (a) SHOW THAT SOLUTIONS OF FORM  $\vec{x}(t) = e^{\lambda t} \vec{v}$  CORRESPOND TO EIGENPAIRS  $(\lambda, \vec{v})$  OF  $A$
- (b) SOLVE CHARACTERISTIC EQN  $0 = p(\lambda) = \det(A - \lambda I)$  TO DETERMINE EIGENVALUES.

HINT:  $A$  is  $2 \times 2$  so  $p(\lambda) = \det 2$  poly.

- (c) FOR EACH  $\lambda$  CALCULATE  $N(A - \lambda I)$  USING G.E.

YOU WILL GET

$$\lambda = 2 \quad N(A - 2I) = \text{Span}\left\{\begin{pmatrix} 1 \\ 2 \end{pmatrix}\right\}$$

$$\lambda = -3 \quad N(A + 3I) = \text{Span}\left\{\begin{pmatrix} 1 \\ -3 \end{pmatrix}\right\}$$

SO  $\exists$  BASIS OF  $\mathbb{R}^2$  CONSISTING OF EIGENVECTORS OF  $A$

- (d) LATER we will show every solution of ODE is of form

$$\vec{x}(t) = c_1 e^{2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 e^{-3t} \begin{pmatrix} 1 \\ -3 \end{pmatrix} \quad \text{g.t.f.}$$

Find particular solution solving  $\vec{x}(0) = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$

HINT: SET UP + SOLVE  $2 \times 2$  LINEAR SYSTEM FOR  $\begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$ .

- (e) SKETCH  $\vec{x}(t)$  IN  $(t, x(t))$ -SPACE.

# ① THEORY ABOUT EIGENVALUES

⑤

THM 3 Let  $A$  be  $n \times n$

- ①  $p(\lambda) = \det(A - \lambda I)$  is a deg  $n$  POLY  
with leading term  $(-1)^n \lambda^n$ .

So by FUNDAMENTAL THM OF ALGEBRA

- ②  $A$  has  $n$  eigenvalues.  
- complex and/or Repeated possible.
- ③ IF  $A \in \mathbb{R}^{n \times n}$  Then evlues come in  
complex conjugate pairs.

PROBLEM: GALOIS THEORY (Abstract Algebra II) tells us  
no formula for  $\lambda$ 's. for  $n \geq 5$

SOLUTION! Use numerical linear algebra algorithms  
to approximate  $\lambda$ 's. (NARAB)

WITH LUCK CAN USE ( $n=3$  or  $4$ )

THM 4

IF  $\alpha_i$ 's are INTEGERS THEN every INTEGER solution  
of  $\lambda^n + \alpha_{n-1} \lambda^{n-1} + \dots + \alpha_1 \lambda + \alpha_0 = 0$   
must be a factor of  $\alpha_0$ .

## (E) SCAFFOLDED PROBLEMS

(6)

- ① FIND ALL ROOTS OF  $p(\lambda) = \lambda^3 + 3\lambda^2 + 5\lambda + 3$ .
- ② WHAT IS  $\alpha_0$ ?
- ③ WHAT DOES THM 4 TELL US?
- ④ USE LONG DIVISION OF POLYNOMIALS TO FACTOR  $p(\lambda)$  AS PRODUCT OF A LINEAR FUNCTION AND A QUADRATIC.
- ⑤ FINISH OFF THE PROBLEM.

DEF A COMPLETE SET OF EIGENVECTORS FOR  $A \in \mathbb{C}^{n \times n}$

IS A SET OF  $n$  EIGENVECTORS OF  $A$  THAT FORM A BASIS FOR  $\mathbb{C}^n$ .

NOTE There is no guarantee a matrix  $A$  has a complete set of eigenvectors.

② LET  $A = \begin{pmatrix} -3 & 1 & -3 \\ 20 & 3 & 10 \\ 2 & -2 & 4 \end{pmatrix}$

③ SHOW  $\sigma(A) = \{3, -2\}$ .

Which eigenvalue is repeated?

④ Calculate  $N(A - 3I)$  and  $N(A + 2I)$

⑤ Can you find a complete set of eigenvectors for  $A$ ?



(3)

COMPLEX EIGENPAIRS + ODEs

(7)

$$\frac{d\vec{x}}{dt} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \vec{x} \quad (*)$$

(a) By calculating eigenpairs of  $A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$  show general solution is

$$\vec{x}(t) = c_1 e^{it} \begin{pmatrix} 1 \\ i \end{pmatrix} + c_2 e^{-it} \begin{pmatrix} 1 \\ -i \end{pmatrix} \quad \text{gief.}$$

(b) The ODE is real but solution is complex. YUK!!

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Use Euler's Formula  $e^{it} = \cos t + i \sin t$  to show

$$\vec{x}(t) = a_1 \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix} + a_2 \begin{pmatrix} \sin t \\ \cos t \end{pmatrix} \quad \text{gief.}$$

(c) SOLVE IVP with  $\vec{x}(0) = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ .

(d) SKETCH SOLUTION IN (c) IN  $(x_1, x_2)$ -PLANE.

(e) Show how solution to (\*) is related to 2nd order ODE

$$u'' + u = 0$$

$$u = u(t)$$

$$u: \mathbb{R} \rightarrow \mathbb{R}.$$

(8)

(F) 7.1.18  $A$  is  $n \times n$ 

(a)  $\sigma(A^T) = \sigma(A)$

This means  $A$  and  $A^T$  have same evales with same algebraic multiplicities.

PF

$$\det(A^T - \lambda I) = \det((A - \lambda I)^T) \\ = \det(A - \lambda I) \quad \text{as } \det B^T = \det B$$

(b)  $\lambda \in \sigma(A) \Leftrightarrow \bar{\lambda} \in \sigma(A^*) \quad A^* = \bar{A}^T$

EG If  $\lambda = 5 + i$  is evale of  $A$  with alg mult 4

Then  $\bar{\lambda} = 5 - i$  is evale of  $A^*$  with alg mult 4

PF  $\lambda \in \sigma(A) \Leftrightarrow \det(A - \lambda I) = 0$

$\Leftrightarrow \det((A - \lambda I)^T) = 0$

$\Leftrightarrow \overline{\det(A - \lambda I)^T} = 0$

$\Leftrightarrow \det((A - \lambda I)^T) = 0$

as  $\det(\bar{B}) = \overline{\det(B)}$

$\Leftrightarrow \det((A - \lambda I)^*) = 0$

$\Leftrightarrow \det(A^* - \bar{\lambda} I) = 0 \Leftrightarrow \bar{\lambda} \in \sigma(A^*)$

(9)

© IF  $A \in \mathbb{R}^{n \times n}$

Then  $\lambda \in \sigma(A) \iff \bar{\lambda} \in \sigma(A)$

i.e. Eigenvalues come in complex conjugate pairs

EX If  $A$  is <sup>real</sup>  $3 \times 3$  and  $\lambda = 5 + 2i$  is an eigenvalue

Then  $\lambda = 5 - 2i$  must also be an eigenvalue

Q If  $A$  is  $n \times n$  where  $n$  is odd what can you conclude about how many eigenvalues of  $A$  must be real?

(PF of 5)

By ①

$$\lambda \in \sigma(A) \iff \bar{\lambda} \in \sigma(A^T)$$

|| as  $A$  is Real

$$\sigma(A^T)$$

||

$$\sigma(A)$$

By (a)

D